

**TECNAMIC**

Dynamic Drive Technology

## FLEXIBLE COUPLINGS

**FLEX**



# FLEX

## FLEXIBLE FLEX COUPLINGS

The Flex coupling combines all the advantages which can be expected of an ideal flexible coupling. It is a torsional flexible coupling which offers a wide spectrum of cases of applications to the technical designers and the engineers by combining the different types of steel flanges for many different applications. Flex is a high flexible tyre coupling which can because of the special builded tyre take an extreme big misalignment at a low restoring force in each direction without noticing this in the wear. Because of a factory-installed joint the tyre can according to standard be radially assembled and disassembled without shifting the connected engines. The transmission of the torque takes place absolutely free from backlash. Thanks to the flexibility of the coupling, impacts, rotary vibrations and noises are effectively absorbed. The tyre with fabric inside is either made of natural rubber or of chloroprene in fire-resistant, antistatic and oil-resistant execution, short called FRAS-execution. The FRAS-tyre is also used in duties with Ex-operations according to the EC directive. Tyres made of natural rubber are suitable for ambient temperatures between -50 °C and +50 °C. Tyres in FRAS-execution are suitable for ambient temperatures between -15 °C and +70 °C.



### TYPE

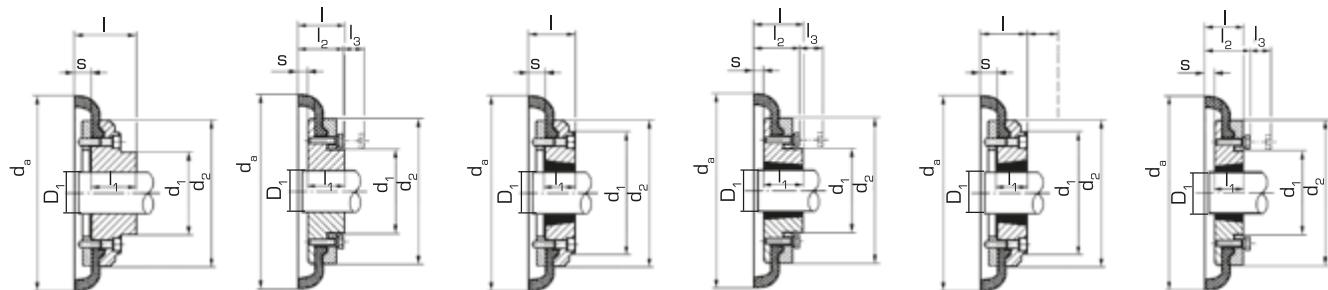
- Standard coupling for finish bore
- Taper bush type
- Combined type standard/taper
- Components can be combined as needed

## FLEXIBLE FLEX COUPLINGS

### WITH TAPER BUSH

The Flex coupling combines the advantages of the elastic couplings with those of the taper bush system: fast and simple assembly of a torsionally flexible connection of shafts and compensation for shaft alignment errors. Flex couplings with taper bush have the advantage that even with greater shaft tolerances there is a backlash-free and at the same time axial fixing of the shaft. In addition the close sliding fit makes axial alignment of the coupling easier.

# FLEX FLANGE B, F, H



► B flange  
40-60

70-250

► F flange  
40-60

70-250

► H flange  
40-60

70-250

Size	Pre. bored	B flange				F flange				H flange				$d_2$	$l_2$	$l_3$	$s$ mm			
		$D_1$ (H7) <sup>1)</sup> max. mm	$d_1$ mm	$l$ mm	$l_1$ mm	Bush	$D_1$ max. mm	$d_1$ mm	$l$ mm	$l_1$ mm	Bush	$D_1$ max. mm	$d_1$ mm	$l$ mm	$l_1$ mm	$d_a$ mm	$d_2$ mm	$l_2$ mm	$l_3$ mm	$s$ mm
D 40	12	30	-	33	22	1008	25	-	33	22	1008	25	-	33	22	104	82	-	-	11
D 50	15	38	79	45	32	1210	32	79	38	25	1210	32	79	38	25	133	100	-	-	12.5
D 60	18	45	70	55	38	1610	42	70	42	25	1610	42	70	42	25	165	125	-	-	16.5
D 70	22	50	80	47	35	2012	50	80	44	32	1610	42	80	42	25	187	144	50	13	11.5
D 80	25	60	97	55	42	2517	60	95	58	45	2012	50	97	45	32	211	167	54	16	12.5
D 90	28	70	112	63.5	49	2517	60	108	59.5	45	2517	60	108	59.5	45	235	188	60	16	13.5
D 100	32	80	125	70.5	56	3020	75	120	65.5	51	2517	60	113	59.5	45	254	216	62	16	13.5
D 110	30	90	128	75.5	63	3020	75	134	63.5	51	3020	75	134	63.5	51	279	233	62	16	12.5
D 120	38	100	143	84.5	70	3525	100	140	79.5	65	3020	75	140	65.5	51	314	264	67	16	14.5
D 140	75	130	178	110.5	94	3525	100	178	81.5	65	3525	100	178	81.5	65	359	311	73	17	16
D 160	75	140	187	117	102	4030	115	197	92	77	4030	115	197	92	77	402	345	78	19	15
D 180	75	150	200	137	114	4535	125	205	112	89	4535	125	205	112	89	470	398	94	19	23
D 200	85	150	200	138	114	4535	125	205	113	89	4535	125	205	113	89	508	429	103	19	24
D 220	85	160	218	154.5	127	5040	125	223	129.5	102	5040	125	223	129.5	102	562	474	118	20	27.5
D 250	85	190	254	161.5	132	-	-	-	-	-	-	-	-	-	-	628	532	125	25	27.5

1) Drill holes H7 with keyway in accordance with DIN 6885/1; tolerance zone JS9 and set screws on the keyway

# TECHNICAL DATA

Size	Max. rotation speed rpm	Torque <sup>1)</sup> Nm			Torsion spring rigidity dyn Nm/rad	Relative damping $\psi$	Moments of inertia <sup>3)</sup> kgm <sup>2</sup>	Weight <sup>3)</sup>	Max. shaft misalignment <sup>4)</sup>		
		nominal $T_{KN}$	max. $T_{kmax}$	changing $T_{Kw}^{2)}$					radial $\Delta K_r$ mm	axial $\Delta K_a$ mm	angular $\Delta K_w$ mm
D 40	4500	24	64	11	285	0.9	0.00148	1.6	1.1	1.3	5.7
D 50	4500	66	160	26	745	0.9	0.0023	2.4	1.3	1.7	7
D 60	4000	127	318	53	1500	0.9	0.0104	4.0	1.6	2.0	8.7
D 70	3600	250	487	81	2350	0.9	0.018	6.2	1.9	2.3	10
D 80	3100	375	759	127	3600	0.9	0.036	9.8	2.1	2.6	12
D 90	3000	500	1096	183	5200	0.9	0.062	14.0	2.4	3.0	13
D 100	2600	675	1517	252	7200	0.9	0.11	20.0	2.6	3.3	15
D 110	2300	875	2137	356	10 000	0.9	0.156	23.5	2.9	3.7	16
D 120	2050	1330	3547	591	17 000	0.9	0.274	33.0	3.2	4.0	18
D 140	1800	2325	5642	940	28 000	0.9	0.51	45.0	3.7	4.6	22
D 160	1600	3770	9339	1556	44 500	0.9	0.849	68.0	4.2	5.3	24
D 180	1500	6270	16 455	2742	78 500	0.9	1.718	92.0	4.8	6.0	28
D 200	1300	9325	23 508	3918	110 000	0.9	2.582	112.0	5.3	6.6	30
D 220	1100	11 600	33 125	5521	160 000	0.9	4.246	152.0	5.8	7.3	33
D 250	1000	14 675	42 740	7124	200 000	0.9	7.01	208.0	6.6	8.2	37

1) Torques for shaft fit with keyway

2) Maximum alternating torque up to  $f = 10$  Hz

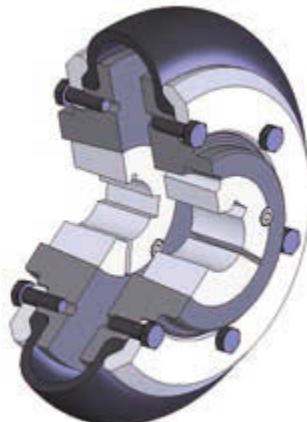
3) The details of weight and moments of inertia apply for medium holes.

4) The values mentioned may occur only separately. At multiple misalignments the values must be reduced (see page 5).

# TAPER BUSHES WITH KEYWAY ACC. TO DIN 6885/1

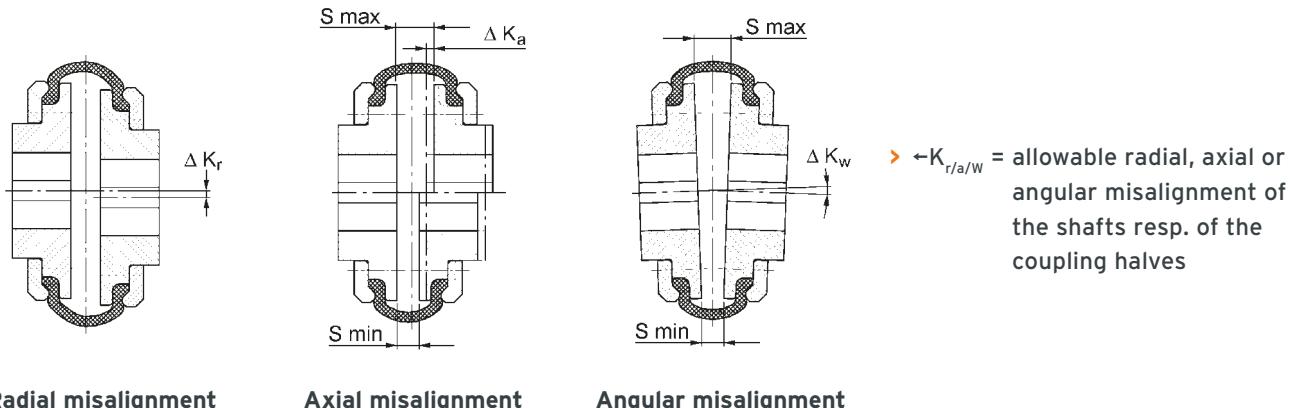
Taper bush no.	Bore ø of available taper bushes mm											
	10	11	12	14	16	18	19	20	22	24*	25*	28
1008	10	11	12	14	16	18	19	20	22	24*	25*	
1210	10	11	12	14	16	18	19	20	22	24	25	28
	30	32										
1610	14	16	18	19	20	22	24	25	28	30	32	35
	38	40	42*									
2012	14	16	18	19	20	22	24	25	28	30	32	35
	38	40	42	45	48	50						
2517	16	18	19	20	22	24	25	28	30	32	35	38
	40	42	45	48	50	55	60	65*				
3020	25	28	30	32	35	38	40	42	45	48	50	55
	60	65	70	75								
3525	35	38	40	42	45	48	50	55	60	65	70	75
	80	85	90	95	100*							
4030	40	42	45	48	50	55	60	65	70	75	80	85
	90	95	100	105	110	115*						
4535	55	60	65	70	75	80	85	90	95	100	105	110
	115	120	125									
5040	70	75	80	85	90	95	100	105	110	115	120	125

► Tolerance JS9



\* These bore holes are with flat keyway in accordance with DIN 6885/3.

# ALLOWABLE MISALIGNMENTS



Radial misalignment

Axial misalignment

Angular misalignment

- The values given for  $\leftarrow K_w$  [mm] =  $S_{max} - S_{min}$  (see page 4) correspond to an angular offset of  $\leftarrow K_w = 4^\circ$ . This permissible angular shaft offset is the largest angular offset of the coupling halves, which may only be fully utilised if there is no axial and radial offset. An angular offset of  $\leftarrow K_w = 2^\circ$  is permissible if axial and radial offsets of  $1/2 \leftarrow K_a$  and  $1/2 \leftarrow K_r$  are present.

## SELECTION

- The torque of the machine  $T_{AN}$  is determined by:  $T_{AN}$  [Nm] =  $9550 \times \frac{P_{Motor}}$  [kW] / n [rpm]

This torque  $T_{AN}$  multiplied by a safety factor  $S$  depending on the application gives the required nominal coupling torque  $T_{KN}$ .

Result:  $T_{KN} \geq S \times T_{AN}$

- In case that bigger shock or changing loads occur we recommend a revision according to DIN 740. An adequate calculation program is available. For such a revision the following information is required:

1. Kind of the driving machine
2. Kind of the driven machine
3. Power of driving and driven machines
4. Rotational speed of operation
5. Shock loads
6. Exciting loads
7. Moments of inertia of load- and driving sides
8. Starts per hour
9. Ambient temperature

## DESIGN EXAMPLE FOR IEC STANDARD MOTORS

### Dates of the plant

Driving machine:

Three-phase motor: Size 280S

Power of the motor: P = 75 kW

Rotation at speed: n = 1500 rpm

up to 50 start-ups per hour

Driven machine: mixer

Ambient temperature: +25 °C

### Layout of the coupling

$$T_{AN}$$
 [Nm] =  $9550 \times \frac{75 \text{ kW}}{1500 \text{ rpm}} = 478 \text{ Nm}$

$$T_{KN} = 2.5 \times 478 \text{ Nm} = 1195 \text{ Nm}$$

(S = 1.75 as per table + 0.75 for start-up frequency greater than 25)

Selection: Flex D 120

$$T_{KN} = 1330 \text{ Nm}$$

# ALLOCATION TO IEC MOTORS

Size of the three-phase motor	Power P of the IEC motors and allocated Flex										Shaft ends	
	3000 rpm		1500 rpm		1000 rpm		750 rpm				Form E DIN 748 part 3 d x l at speed approx.	
	P kw	Flex size	P kw	Flex size	P kw	Flex size	P kw	Flex size	3000 rpm	1500 rpm and less		
56	0.09	D40	0.06	D40	0.037	D40	-	-	9 x 20			
	0.12	D40	0.09	D40	0.045	D40						
63	0.18	D40	0.12	D40	0.06	D40	-	-	11 x 23			
	0.25	D40	0.18	D40	0.09	D40						
71	0.37	D40	0.25	D40	0.18	D40	0.09	D40	14 x 30			
	0.55	D40	0.37	D40	0.25	D40	0.12	D40				
80	0.75	D40	0.55	D40	0.37	D40	0.18	D40	19 x 40			
	1.1	D40	0.75	D40	0.55	D40	0.25	D40				
90 S	1.5	D50	1.1	D50	0.75	D50	0.37	D50	24 x 50			
90 L	2.2	D50	1.5	D50	1.1	D50	0.55	D50	24 x 50			
100 L	3	D50	2.2	D50	1.5	D50	0.75	D50	28 x 60			
	-		3	D50	-		1.1	D50				
112 M	4	D50	4	D50	2.2	D50	1.5	D50	28 x 60			
132 S	5.5	D60	5.5	D60	3	D60	2.2	D60	38 x 80			
	7.5	D60	-		-		-					
132 M	-		7.5	D60	4	D60	3	D60	38 x 80			
			-		5.5	D60	-					
160 M	11	D70	11	D70	7.5	D70	4	D70	42 x 110			
	15	D70	-		-		5.5	D70				
160 L	18.5	D70	15	D70	11	D70	7.5	D70	42 x 110			
180 M	22	D70	18.5	D70	-		-		48 x 110			
180 L	-		22	D70	15	D80	11	D80	48 x 110			
200 L	30	D80	30	D80	18.5	D80	15	D80	55 x 110			
	37	D80	-		22	D80	-					
225 S	-		37	D90	-		18.5	D90	55 x 110	60 x 140		
225 M	45	D80	45	D100	30	D100	22	D100	55 x 110	60 x 140		
250 M	55	D80	55	D100	37	D100	30	D100	60 x 140	65 x 140		
280 S	75	D80	75	D110	45	D110	37	D120	65 x 140	75 x 140		
280 M	90	D90	90	D120	55	D120	45	D120	65 x 140	75 x 140		
315 S	-		110	D120	75	D120	55	D120	65 x 140	80 x 170		
315 M	-		132	D140	90	D140	75	D140	65 x 140	80 x 170		
315 L	-		160	D140	110	D140	90	D140	65 x 140	80 x 170		
	-		200	D140	132	D140	110	D160				
355 L	-		250	D160	160	D160	132	D180	75 x 140	95 x 170		
	-		315	D160	200	D160	160	D180				
	-		-		250	D160	200	D180				
400 L	-		355	D180	315	D180	250	D180	80 x 170	100 x 210		
	-		400	D180	-		-					

- As proposed in the table for surface cooled three-phase motors with cage rotor acc. to DIN 42673, page 1 (data for motor 56, 63, 71, 80, 315 L, 355 L, 400 L, see catalogue Siemens). This allocation is a preliminary selection for normal conditions of operation. For conditions of operation under shock and changing loads the selection must be made according to page 5.

## **SAFETY FACTOR S**

## Assignment of load characteristics according to type of working machine

<b>DREDGERS</b> S Bucket conveyor S Landing gear (caterpillar) M Landing gear (rail) M Manoeuvring winches M Pumps S Impellers S Cutter heads M Slewинг gear	<b>RUBBER MACHINERY</b> S Extruders M Calenders S Kneading mills M Mixers S Rolling mills	<b>PUMPS</b> S Piston pumps G Centrifugal pumps (light liquids) M Centrifugal pumps (viscous liquids) S Plunger pumps S Press pumps
<b>GENERATORS, TRANSFORMERS</b> M Frequency transformers M Generators M Welding generators	<b>WOOD WORKING MACHINES</b> S Barkers M Planing machines G Wood working machines S Saw frames	<b>STONE AND CLAY WORKING MACHINES</b> S Crusher S Rotary ovens S Hammer mills S Ball mills S Tube mills S Beater mills S Brick presses
<b>CHEMICAL INDUSTRY</b> M Cooling drums M Mixers G Agitators (liquid material) M Agitators (semi-liquid material) M Drying drums G Centrifuges (light) M Centrifuges (heavy)	<b>CRANES</b> G Luffing gear block S Travelling gear G Hoist gear M Slewing gear M Derricking jib gear	<b>TEXTILE MACHINES</b> M Batchers M Printing and dyeing machines M Tanning vats M Willows M Looms
<b>OIL INDUSTRY</b> M Pipeline pumps S Rotary drilling equipment	<b>PLASTIC INDUSTRY MACHINES</b> M Extruders M Calenders M Mixers M Crushers	<b>COMPRESSORS</b> S Piston compressors M Turbo compressors
<b>CONVEYORS</b> M Pit-head winches S Winding engines M Jointed-band conveyors G Belt conveyors (bulk material) M Belt conveyors (piece goods) M Band pocket conveyors M Chain conveyors M Circular conveyors M Load elevators G Bucket conveyors for flour M Passenger lifts M Plate conveyors M Screw conveyors M Ballast elevators S Inclined hoists M Steel belt conveyors M Drag chain conveyors	<b>METAL WORKING MACHINES</b> M Plate bending machines S Plate straightening machines S Hammers S Metal planning machines S Presses M Shears S Forging presses S Punch presses G Countershafts, line shafts M Machine tools (main drives) G Machine tools (auxiliary drives)	<b>METAL ROLLING MILLS</b> S Plate shears M Manipulator for turning sheets S Ingot pushers S Ingot and slabbing-mill train S Ingot handling machinery M Wire drawing benches S Descaling machines S Thin plate mills S Heavy and medium plate mills M Winding machines (strip and wire) S Cold rolling mills
<b>BLOWERS, VENTILATORS</b> M Rotary piston blowers G Blowers (axial/radial) M Cooling tower fans M Induced draught fans G Turbo blowers	<b>FOOD INDUSTRY MACHINERY</b> G Bottling and container filling machines M Kneading machines M Mash tubs G Packaging machines M Cane crushers M Cane cutters S Cane mills M Sugar beet cutters M Sugar beet washing machines	M Chain tractor S Billet shears M Cooling beds M Cross tractor M Roller tables (light) S Roller tables (heavy) M Roller straighteners S Tube welding machines M Trimming shears S Cropping shears S Continuous casting plant M Rollers adjustment drive S Manipulators
<b>BUILDING MACHINERY</b> S Hoists G Concrete mixers S Road construction machinery	<b>PAPER MACHINES</b> S Couches S Glazing cylinders M Pulper S Pulp grinders M Calenders S Wet presses S Willow S Suction presses S Suction rolls S Drying cylinders	<b>LAUNDRIES</b> M Tumblers M Washing machines
		<b>WATER TREATMENT</b> M Aerators M Screw pumps

Operating factor S			
Driving machines	Load characteristics of the working machine		
	G	M	S
Electric motors, turbines, hydraulic motors	1	1.75	2.5
Piston machines 4-6 cylinders, degree of nonuniformity 1:100 - 1:200	1.25	2	2.75
Piston machines 1-3 cylinders, degree of nonuniformity up to 1:100	1.5	2.25	3

- The operating factor S takes account of up to 25 start-ups per hour.

- With up to 120 start-ups per hour the factor S must be increased by 0.75.

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